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Stability of solutions of the Einstein equations

Solutions of the Einstein-Vacuum equations tending to the Minkowski spacetime at infinity

Talk:

- Setting of the problem
- Questions - Solutions
- Solution by D. Christodoulou and S. Klainerman in 'The global nonlinear stability of the Minkowski space'
- Solution with more general initial data (B)
- Structures and ideas used in the proof

Solutions of the Einstein-Vacuum (EV) equations:

$$R_{\mu\nu} = 0 . \quad (1)$$

Spacetimes (M, g) , where M is a four-dimensional, oriented, differentiable manifold and g is a Lorentzian metric obeying (1).

Is there any non-trivial, asymptotically flat initial data whose maximal development is complete?

Works by many authors:

Y. Choquet-Bruhat, R. Geroch, R. Penrose, S. Hawking,
D. Christodoulou, S. Klainerman, H. Lindblad,
I. Rodnianski, F. Nicolò, H. Friedrich
and more.

- **Y. Choquet-Bruhat (1952):**

**'Théorème d'existence pour certain systèmes
d'équations aux dérivées partielles nonlinéaires':**

- Cauchy problem for the Einstein equations,
- **local** in time, existence and uniqueness of solutions,
- reducing the Einstein equations to wave equations, introducing harmonic (or wave) coordinates.

Choquet-Bruhat proved the well-posedness of the local Cauchy problem in these coordinates.

- **Y. Choquet-Bruhat and R. Geroch**, stating the **existence of a unique maximal future development for each given initial data set.**

⇒ **Question:** Is this maximal development **complete**?

- **R. Penrose**

gave the answer in his **incompleteness theorem**:

Consider **initial data**, where the initial Cauchy hypersurface H is non-compact and complete. If H contains a **closed trapped surface** S , the boundary of a compact domain in H , then the corresponding **maximal future development is incomplete**.

Closed trapped surface S: An infinitesimal displacement of S in M towards the future along the outgoing null geodesic congruence results in a pointwise decrease of the area element.

D. Christodoulou

A closed trapped surface can form in the evolution, starting from initial data not containing any such surfaces.

- **Theorem of Penrose and its extensions by S. Hawking and R. Penrose**

⇒ Question, formulated at the beginning.

Answer

Joint work of **D. Christodoulou** and **S. Klainerman**
([CK], 1993),

'**The global nonlinear stability of the Minkowski space**'.

Every asymptotically flat initial data which is globally close to the trivial data gives rise to a solution which is a complete spacetime tending to the Minkowski spacetime at infinity along any geodesic.

- No additional restriction on the data.
- No use of a preferred system of coordinates
- Relied on the invariant formulation of the E-V equations.
- **Precise description of the asymptotic behaviour at null infinity.**

H. Lindblad and I. Rodnianski:

'Global existence for the EV equations in wave coordinates'

- **Global stability of Minkowski space for the EV equations in harmonic (wave) coordinate gauge**
- for the set of **restricted data coinciding with the Schwarzschild solution in the neighbourhood of space-like infinity.**
- Result contradicts beliefs that wave coordinates are 'unstable in the large' and provides an alternative approach to the stability problem
- Result is less precise as far as the asymptotic behaviour is concerned
- Focus on giving a solution in a physically interesting wave coordinate gauge

H. Lindblad and I. Rodnianski:

'The global stability of Minkowski space-time in harmonic gauge'

- Stability for **EV scalar field** equations
- Less decay of 'tail of the metric'

New Result [B]

More general asymptotically flat initial data with

less decay and

one less derivative than in [CK]

yielding a solution which is a complete spacetime, tending to the Minkowski spacetime at infinity along any geodesic.

⇒ Have **finite energy**

R. Bartnik's formulation of the positive mass theorem applies.

R. Bartnik

Positive mass theorem:

If we are given an asymptotically flat, connected, complete, 3-dimensional manifold (H, g) with

$$\|g_{ij} - \delta_{ij}\|_{2,2,-\frac{1}{2}} \leq \epsilon$$

and integrable scalar curvature $R \geq 0$.

Then the mass

$$m_{ADM} \geq 0$$

and $m_{ADM} = 0$ if and only if (H, g) is globally flat.

Initial data set: A triplet (H, \bar{g}, k) with (H, \bar{g}) being a three-dimensional complete Riemannian manifold and k a two-covariant symmetric tensorfield on H , satisfying the **constraint equations**:

$$\begin{aligned}\nabla^i k_{ij} - \nabla_j \text{tr}k &= 0 \\ R - |k|^2 + (\text{tr}k)^2 &= 0.\end{aligned}$$

Evolution equations:

$$\begin{aligned}\frac{\partial \bar{g}_{ij}}{\partial t} &= 2\Phi k_{ij} \\ \frac{\partial k_{ij}}{\partial t} &= \nabla_i \nabla_j \Phi - (R_{ij} + k_{ij} \text{tr} k - 2k_{im} k_j^m) \Phi\end{aligned}$$

Constraint equations:

$$\begin{aligned}\nabla^i k_{ij} - \nabla_j \text{tr} k &= 0 \\ R + (\text{tr} k)^2 - |k|^2 &= 0\end{aligned}$$

A general **asymptotically flat initial data set** (H, \bar{g}, k) :

An initial data set such that

- the complement of a compact set in H is diffeomorphic to the complement of a closed ball in \mathbb{R}^3
- and there exists a coordinate system (x^1, x^2, x^3) in this complement relative to which the metric components

$$\begin{aligned}\bar{g}_{ij} &\rightarrow \delta_{ij} \\ k_{ij} &\rightarrow 0\end{aligned}$$

sufficiently rapidly as $r = (\sum_{i=1}^3 (x^i)^2)^{\frac{1}{2}} \rightarrow \infty$.

In [CK], consider the following

strongly asymptotically flat initial data set:

An initial data set (H, \bar{g}, k) , where \bar{g} and k are sufficiently smooth and there exists a coordinate system (x^1, x^2, x^3) defined in a neighbourhood of infinity such that,

as $r = (\sum_{i=1}^3 (x^i)^2)^{\frac{1}{2}} \rightarrow \infty$:

$$\bar{g}_{ij} = \left(1 + \frac{2M}{r}\right) \delta_{ij} + o_4 \left(r^{-\frac{3}{2}}\right) \quad (2)$$

$$k_{ij} = o_3 \left(r^{-\frac{5}{2}}\right), \quad (3)$$

where M denotes the mass.

The strongly asymptotically flat initial data set has to satisfy a certain smallness assumption.

They introduce

$$\begin{aligned}
 Q(x_{(0)}, b) = & \sup_H \left(b^{-2} (d_0^2 + b^2)^3 |Ric|^2 \right) \\
 & + b^{-3} \left(\int_H \sum_{l=0}^3 (d_0^2 + b^2)^{l+1} |\nabla^l k|^2 \right. \\
 & \left. + \int_H \sum_{l=0}^1 (d_0^2 + b^2)^{l+3} |\nabla^l B|^2 \right) \quad (4)
 \end{aligned}$$

$d_0(x) = d(x_{(0)}, x)$: the Riemannian geodesic distance between the point x and a given point $x_{(0)}$ on H .

b : a positive constant.

∇^l : the l -covariant derivatives.

B (Bach tensor): the following symmetric, traceless 2-tensor

$$B_{ij} = \epsilon_j^{ab} \nabla_a (R_{ib} - \frac{1}{4} g_{ib} R) .$$

Global Smallness Assumption:

A strongly asymptotically flat initial data set is said to satisfy the **global smallness assumption** if the metric \bar{g} is complete and there exists a sufficiently small positive ϵ such that

$$\inf_{x_{(0)} \in H, b \geq 0} Q(x_{(0)}, b) < \epsilon . \quad (5)$$

One version of the **main theorem in [CK]**:

Theorem 1. *Any strongly asymptotically flat, maximal, initial data set that satisfies the global smallness assumption (5), leads to a **unique, globally hyperbolic, smooth and geodesically complete solution** of the E - V equations foliated by a normal, maximal time foliation. This development is **globally asymptotically flat**.*

Proof for more general initial data in the following sense [B]:

We consider an asymptotically flat initial data set (H_0, \bar{g}, k) for which there exists a coordinate system (x^1, x^2, x^3) in a neighbourhood of infinity such that with $r = (\sum_{i=1}^3 (x^i)^2)^{\frac{1}{2}} \rightarrow \infty$, it is:

$$\bar{g}_{ij} = \delta_{ij} + o_3(r^{-\frac{1}{2}}) \quad (6)$$

$$k_{ij} = o_2(r^{-\frac{3}{2}}) . \quad (7)$$

Global smallness assumption:

$$\begin{aligned}
 Q(a, 0) &= a^{-1} \left(\int_{H_0} \left(|k|^2 + (a^2 + d_0^2) |\nabla k|^2 \right. \right. \\
 &\quad \left. \left. + (a^2 + d_0^2)^2 |\nabla^2 k|^2 \right) d\mu_{\bar{g}} \right. \\
 &\quad \left. + \int_{H_0} \left((a^2 + d_0^2) |Ric|^2 \right. \right. \\
 &\quad \left. \left. + (a^2 + d_0^2)^2 |\nabla Ric|^2 \right) d\mu_{\bar{g}} \right) \\
 &< \epsilon .
 \end{aligned} \tag{8}$$

a : positive scale factor.

Main Theorem [B]:

Theorem 2. *Any asymptotically flat, maximal initial data set satisfying the global smallness assumption, leads to a **unique, globally hyperbolic, smooth and geodesically complete solution of the EV-equations, foliated by the level sets of a maximal time function. This development is globally asymptotically flat.***

- **Invariant formulation of the E-V equations**
- No use of a preferred coordinate system
- **Asymptotic behaviour** given in a **precise** way
- **Appropriate foliation of the spacetime**
- **Bianchi identity** for the **Weyl tensor** W , having all the symmetry properties of the curvature tensor, in addition is traceless and satisfies the Bianchi equations

$$D_{[\epsilon} W_{\alpha\beta]\gamma\delta} = 0 .$$

- **Bel-Robinson tensor:**

Associate to a Weyl field a tensorial quadratic form:

- a 4-covariant tensorfield
- being fully symmetric and trace-free.

$$Q_{\alpha\beta\gamma\delta} = \frac{1}{2} (W_{\alpha\rho\gamma\sigma} W_{\beta}{}^{\rho}{}_{\delta}{}^{\sigma} + {}^*W_{\alpha\rho\gamma\sigma} {}^*W_{\beta}{}^{\rho}{}_{\delta}{}^{\sigma}) .$$

It satisfies the following positivity condition:

$$Q (X_1, X_2, X_3, X_4) \geq 0$$

X_1, X_2, X_3, X_4 future-directed timelike vectors. For W satisfying the Bianchi equations:

$$D^{\alpha} Q_{\alpha\beta\gamma\delta} = 0 .$$

- A **general spacetime** has **no symmetries**, that is, the conformal isometry group is trivial.

⇒ Use **Minkowski** as **background**.

- **Spacetime** → **Minkowski** as $t \rightarrow \infty$. Minkowski having a large **conformal isometry group**. Define in the limit an action of a subgroup.

- **Extend this action backwards in time** up to the initial hypersurface → obtain an **action** of the said subgroup **globally**.

- Apply **Noether's principle (in a generalized way)**
⇒ **Background vacuum solution**

- **Solution constructed** as the corresponding development of the initial data

Constructing a set of **quantities whose growth can be controlled in terms of the quantities themselves**.

Main structures of the spacetime used in the proof

Comparison argument with the **Minkowski** spacetime:

- **Canonical spacelike foliation**
- **Null structure**
- **Conformal group structure**

The (t, u) **foliations** of the spacetime define a codimension 2 foliation by 2-surfaces

$$S_{t,u} = H_t \cap C_u, \quad (9)$$

the intersection between H_t (foliation by t) and a u -null-hypersurface C_u (foliation by u).

Foliation by **time function** t with **lapse function**

$$\Phi(t, x) = (-\langle Dt, Dt \rangle)^{-\frac{1}{2}}$$

with D denoting the covariant differentiation on the spacetime M , and second fundamental form k .

Foliation by **optical function** u , a solution of the **Eikonal equation**:

$$g^{\alpha\beta} \frac{\partial u}{\partial x^\alpha} \frac{\partial u}{\partial x^\beta} = 0.$$

Crucial Foliation:

The **asymptotic behaviour** of the **curvature tensor** R and the **Hessian** of t and u can only be **fully described** by decomposing them into **components tangent to** $S_{t,u}$.

Achieve this

⇒ by introducing

null pairs consisting of 2 future-directed null vectors e_4 and e_3 orthogonal to $S_{t,u}$ with e_4 tangent to C_u and

$$\langle e_4, e_3 \rangle = -2 . \quad (10)$$

A null pair together with an orthonormal frame e_1, e_2 on $S_{t,u}$ forms a **null frame**.

The **null decomposition** of a tensor relative to a null frame e_4, e_3, e_2, e_1 is obtained by taking **contractions** with the vectorfields e_4, e_3 .

Also define

$$\tau_-^2 := 1 + u^2 .$$

Null decomposition of the Riemann curvature tensor of an E-V spacetime:

$$R_{A3B3} = \underline{\alpha}_{AB} \quad (11)$$

$$R_{A334} = 2 \underline{\beta}_A \quad (12)$$

$$R_{3434} = 4 \rho \quad (13)$$

$${}^*R_{3434} = 4 \sigma \quad (14)$$

$$R_{A434} = 2 \beta_A \quad (15)$$

$$R_{A4B4} = \alpha_{AB} \quad (16)$$

with

- $\alpha, \underline{\alpha}$: S -tangent, symmetric, traceless tensors
- $\beta, \underline{\beta}$: S -tangent 1-forms
- ρ, σ : scalars .

Obtained the following **properties for the null components of the curvature tensor** on each hypersurface H_t :

$$\begin{aligned}
 & \int_{H_t} \tau_-^2 |\underline{\alpha}|^2 + \int_{H_t} r^2 |\underline{\beta}|^2 \\
 & + \int_{H_t} r^2 |\rho|^2 + \int_{H_t} r^2 |\sigma|^2 \\
 & + \int_{H_t} r^2 |\beta|^2 + \int_{H_t} r^2 |\alpha|^2 \\
 & + \text{'' } \int_{H_t} \text{first derivatives '' } \leq \epsilon
 \end{aligned}$$

Components decaying like

$$\begin{aligned}
 \underline{\alpha} &= O(r^{-1} \tau_-^{-\frac{3}{2}}) \\
 \underline{\beta} &= O(r^{-2} \tau_-^{-\frac{1}{2}}) \\
 \rho, \sigma, \alpha, \beta &= o(r^{-\frac{5}{2}})
 \end{aligned}$$

Whereas in [CK] the null components have the **decay properties**:

$$\begin{aligned}\underline{\alpha} &= O(r^{-1} \tau_-^{-\frac{5}{2}}) \\ \underline{\beta} &= O(r^{-2} \tau_-^{-\frac{3}{2}}) \\ \rho &= O(r^{-3}) \\ \sigma &= O(r^{-3} \tau_-^{-\frac{1}{2}}) \\ \alpha, \beta &= o(r^{-\frac{7}{2}})\end{aligned}$$

[B]:

Control

One derivative of curvature (Ricci) in H . For Ric including corresponding weights according to (8):

$$\mathbf{Ric} \in \mathbf{W}^{1,2}(\mathbf{H})$$

Trace Lemma gives

\Rightarrow Gauss curvature in the leaves of the u -foliation S :

$$\mathbf{K} \in \mathbf{L}^4(\mathbf{S})$$

[CK]:

Control

Two derivatives of curvature in $L^2(H)$. For Ric including weights as in (4):

$$\mathbf{Ric} \in \mathbf{L}^\infty(\mathbf{H})$$

\Rightarrow also $K \in L^\infty(S)$

We also **control**

Two derivatives of the **second fundamental form** k

\Rightarrow by Sobolev inequalities

$$\mathbf{k} \in \mathbf{L}^\infty(\mathbf{H})$$

\Rightarrow

$$(\text{components of } k) \in L^\infty(S)$$

Main Steps of the Proof

One Large Bootstrap - More Small Bootstraps

1. Estimate an appropriate quantity $Q_1(W)$, integral over H_t involving Bel-Robinson tensor Q of Lie derivative of W .
At time t : can be calculated by its value at $t = 0$ and an integral from 0 to t , both controlled.
2. **Weyl tensor W** verifying the Bianchi equations, controlled through $Q_1(W)$ by a **comparison argument**.
3. **Geometric quantities** determined from **curvature assumptions** using elliptic estimates, evolution equations, Sobolev inequalities, etc.

$Q_1(W)$ is given as follows:

$$Q_1(W) = Q_0 + Q_1$$

with Q_0 and Q_1 being the subsequent integrals,
and for $\bar{K} = K + T$,

$$\begin{aligned} Q_0(t) &= \int_{H_t} Q(W)(\bar{K}, T, T, T) \\ Q_1(t) &= \int_{H_t} Q(\hat{\mathcal{L}}_S W)(\bar{K}, T, T, T) \\ &\quad + \int_{H_t} Q(\hat{\mathcal{L}}_T W)(\bar{K}, \bar{K}, T, T) . \end{aligned}$$

Obtain the estimates of the angular derivatives of our curvature components directly from the Bianchi equations.

In the work [CK]: introduced rotational vectorfields to obtain the corresponding angular derivatives.

Here, no rotational vectorfields are needed.

Bootstrapping

Local \Rightarrow Global

- **Bootstrap assumptions:** Initial assumptions on the main geometric quantities of the 2 foliations, i.e. $\{H_t\}$ and $\{C_u\}$.
- **Local existence theorem**
 \rightarrow local existence
- **Bootstrap argument** together with evolution equations
 \rightarrow global existence

To Point 3 - Estimating Geometric Quantities

Fundamental form χ of S relative to C :

$$\chi(X, Y) = g(D_X L, Y)$$

for any pair of vectors $X, Y \in T_p S$ and L generating vector-field of C .

Estimating χ from the propagation equation

$$\frac{\partial \text{tr} \chi}{\partial s} + \frac{1}{2} (\text{tr} \chi)^2 + |\hat{\chi}|^2 = 0 \quad (17)$$

and the elliptic system on each section S_s of C

$$\text{div} \hat{\chi}_a = \frac{1}{2} d_a \text{tr} \chi + f_a \quad (18)$$

where

f_a involves curvature.

Assuming estimates for the spacetime **curvature** on the right hand side of (18)

\Rightarrow

To obtain estimates for the **quantities controlling the geometry** of C as described by its foliation $\{S_s\}$.

Closing the **bootstrap** arguments.

Energy and Linear Momentum

Energy and linear momentum
are
well-defined and conserved.

Definitions (ADM) in a hypersurface H of the spacetime:

Let $S_r = \{|x| = r\}$ be the coordinate sphere of radius r and dS_j the Euclidean oriented area element of S_r .

- Total Energy

$$E = \frac{1}{4} \lim_{r \rightarrow \infty} \int_{S_r} \sum_{i,j} (\partial_i \bar{g}_{ij} - \partial_j \bar{g}_{ii}) dS_j ,$$

- Linear Momentum

$$P^i = -\frac{1}{2} \lim_{r \rightarrow \infty} \int_{S_r} (k_{ij} - \bar{g}_{ij} \text{tr} k) dS_j ,$$

Open Question:

What is the **sharp criteria** for **non-trivial asymptotically flat initial data sets** to give **rise to a maximal development that is complete?**